

What is and what should be 'Higher Dimensional Group Theory' ? Liverpool

Ronnie Brown

December 4, 2009

What should be higher dimensional group theory?

What should be higher dimensional group theory?

Optimistic answer:

What should be higher dimensional group theory?

Optimistic answer:

Real analysis

What should be higher dimensional group theory?

Optimistic answer:

Real analysis \subseteq many variable analysis

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Group theory

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What is 1-dimensional about group theory?

We all use formulae on a line (more or less):

$$w = ab^2a^{-1}b^3a^{-17}c^5$$

subject to the relations $ab^2c = 1$, say.

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What might be the logic of 2-dimensional (or 17-dimensional) formulae?

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The idea is that we may need to get away from 'linear' thinking in order to express intuitions clearly.

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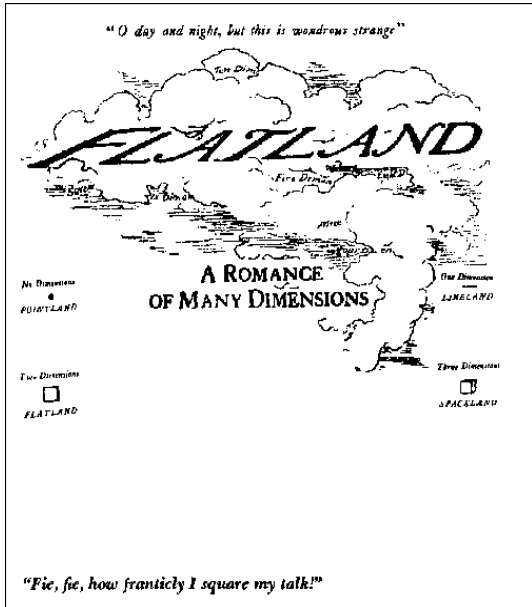
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But we seem to need a linear formula to express the general law

$$a \times (b + c) = a \times b + a \times c.$$



Published in 1884,
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internet.

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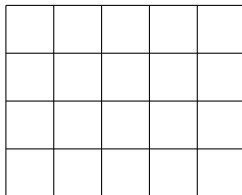
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Consider the figures:

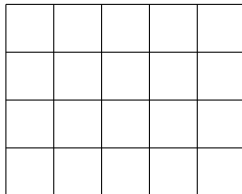
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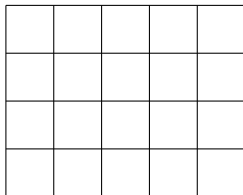


Consider the figures:



From left to right gives **subdivision**.

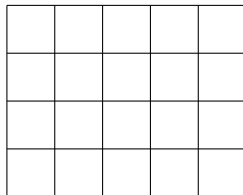
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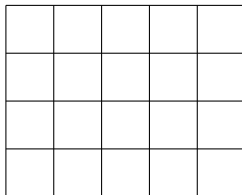


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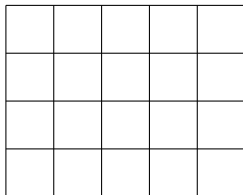
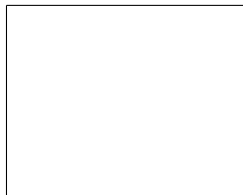
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Algebraic inverses to subdivision.

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From left to right gives **subdivision**.

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What we need for local-to-global problems is:

Algebraic inverses to subdivision.

We know how to cut things up, but how to control algebraically putting them together again?

Look towards

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Look towards
higher dimensional,

Look towards
higher dimensional,
noncommutative methods

Look towards
higher dimensional,
noncommutative methods
for local-to-global problems

Look towards
higher dimensional,
noncommutative methods
for local-to-global problems
and contributing to the unification of mathematics.

Higher dimensional group theory cannot exist (it seems)!

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First try: A 2-dimensional group should be a set G with two group operations \circ_1, \circ_2 each of which is a morphism

$$G \times G \rightarrow G$$

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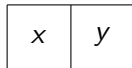
$$G \times G \rightarrow G$$

for the other.

Write the two group operations as:



$$x \circ_1 z$$



$$x \circ_2 y$$

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This is another indication that a '2-dimensional formula' can be
more comprehensible than a 1-dimensional formula!

Theorem Let X be a set with two binary operations \circ_1, \circ_2 , each with identities e_1, e_2 , and satisfying the interchange law. Then the two binary operations coincide, and are commutative and associative.

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We write then e for e_1 and e_2 .

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$$\begin{bmatrix} x & e \\ e & w \end{bmatrix}$$

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$$X \circ_1 W = X \circ_2 W.$$

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$$\begin{bmatrix} x & e \\ e & w \end{bmatrix}$$

So we write \circ for each of \circ_1, \circ_2 .

$$X \circ_1 W = X \circ_2 W.$$

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We leave the proof of associativity to you. This completes the proof.

$$x \circ_1 w = x \circ_2 w.$$

$$y \circ z = z \circ y.$$

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Dreams shattered!

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Dreams shattered!

Back to basics!

How does group theory work in mathematics?

Dreams shattered!

Back to basics!

How does group theory work in mathematics?

Symmetry

Dreams shattered!

Back to basics!

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Symmetry

An abstract algebraic structure, e.g. in number theory,
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Dreams shattered!

Back to basics!

How does group theory work in mathematics?

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Paths in a space: fundamental group

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Algebra structuring space

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F.W. Lawvere: The notion of space is associated with representing motion.

Algebra structuring space

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How can algebra structure space?

[The following graphics were accompanied by the tying of string on a copper pentoil knot. Then a member of the audience was invited to help take the loop off the knot!]

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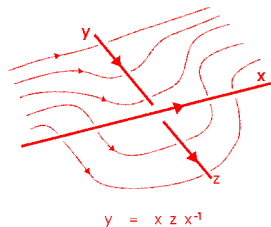
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Moving in the
space around
a knot

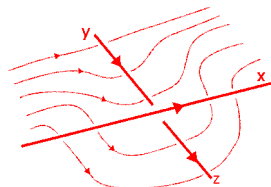


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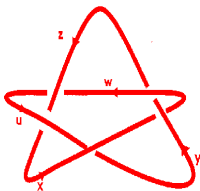
Relation at a crossing

Moving in the space around a knot



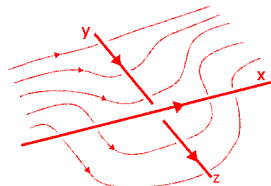
$$y = x z x^{-1}$$

Relation at a crossing



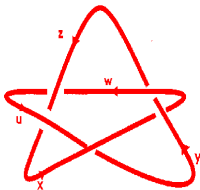
$$x y x y x y^{-1} x^{-1} y^{-1} x^{-1} y^{-1} = 1$$

Moving in the space around a knot

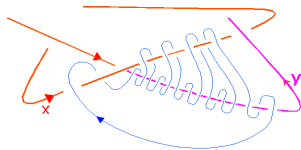


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Local and global issue.

Local and global issue.
Use rewriting of relations.

Local and global issue.

Use rewriting of relations.

Classify the ways of pulling the loop off the knot!

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Groupoids to the rescue

Groupoids to the rescue

Groupoid: underlying geometric structure is a graph

$$G_0 \xrightarrow{i} G \begin{array}{c} \xrightarrow{s} \\ \xrightarrow{t} \end{array} G_0$$

such that $si = ti = 1$. Write $a : sa \rightarrow ta$.

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So G is a small category, and we assume all $a \in G$ are invertible.

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$$(\text{groups}) \subseteq (\text{groupoids})$$

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Groupoids have a partial multiplication, and this opens the door into the world of [partial algebraic structures](#).

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Higher dimensional algebra: algebra structures with partial operations defined under geometric conditions.

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Higher dimensional algebra: algebra structures with partial operations defined under geometric conditions.

Allows new combinations of algebra and geometry, new kinds of mathematical structures, and new ways of describing their inter-relations.

Theorem Let G be a set with two groupoid compositions satisfying the interchange law (a double groupoid). Then G contains a family of abelian groups.

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Masses of algebraic and geometric examples, linking with classical themes, particularly crossed modules. Rich algebraic structures!

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Are there applications in geometry?

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344,000 hits recently

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How did I get into this area?

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Fundamental group $\pi_1(X, a)$ of a space with base point.

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van Kampen Theorem: Calculate the fundamental group of a union.

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If $U \cap V$ is not connected, where to choose the basepoint?

Fundamental group $\pi_1(X, A)$ on a set A of base points.

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Fundamental group $\pi_1(X, A)$ on a set A of base points.

Alexander Grothendieck

.....people are accustomed to work with fundamental groups and generators and relations for these and stick to it, **even in contexts when this is wholly inadequate**, namely when you get a clear description by generators and relations only when working simultaneously with a whole bunch of base-points chosen with care - or equivalently **working in the algebraic context of groupoids**, rather than groups. Choosing paths for connecting the base points natural to the situation to one among them, and reducing the groupoid to a single group, will then **hopelessly destroy the structure and inner symmetries of the situation**, and result in a mess of generators and relations no one dares to write down, because everyone feels they won't be of any use whatever, and just confuse the picture rather than clarify it. I have known such perplexity myself a long time ago, namely in Van Kampen type situations, whose **only understandable formulation** is in terms of (amalgamated sums of) groupoids.

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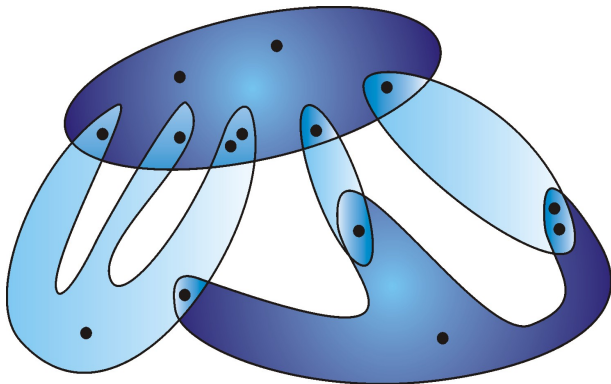
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For all of 1-dimensional homotopy theory, the use of groupoids gives **more powerful theorems with simpler proofs.**

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Groupoids in higher homotopy theory?

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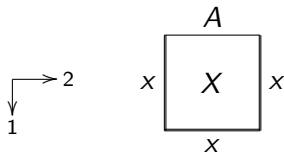
Groupoids in higher homotopy theory?

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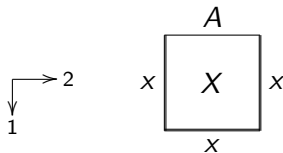


where thick lines show constant paths.

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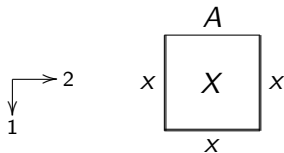
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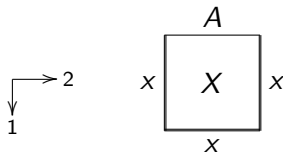
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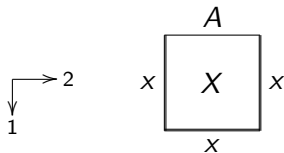
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Brown-Higgins 1974 $\rho_2(X, A, C)$:

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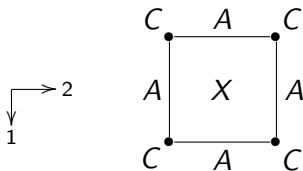
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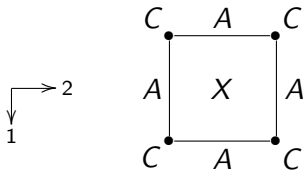
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Brown-Higgins 1974 $\rho_2(X, A, C)$: homotopy classes **rel vertices**
of maps $[0, 1]^2 \rightarrow X$ with edges to A and vertices to C

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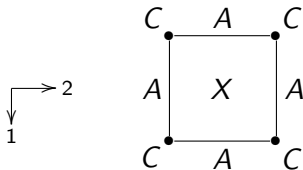


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$$\rho_2(X, A, C) \begin{matrix} \rightrightarrows \\ \rightrightarrows \\ \rightrightarrows \end{matrix} \pi_1(A, C) \begin{matrix} \rightrightarrows \\ \rightrightarrows \end{matrix} C$$

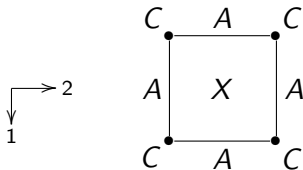
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Childish idea:

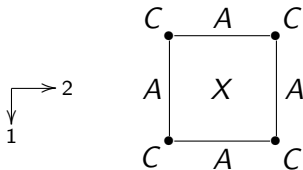
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Childish idea: glue two square if the right side of one is the same as the left side of the other.

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Childish idea: glue two square if the right side of one is the same as the left side of the other. [Geometric condition](#)

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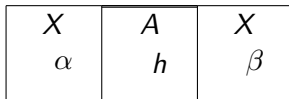
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There is a horizontal composition $\langle\langle\alpha\rangle\rangle +_2 \langle\langle\beta\rangle\rangle$ of classes in $\rho_2(X, A, C)$, where thick lines show constant paths.

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To show $+_2$ well defined,

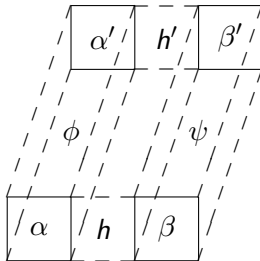
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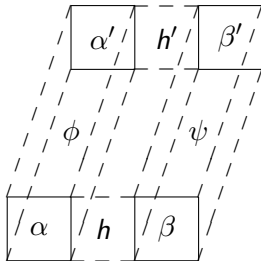
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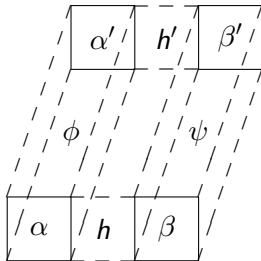


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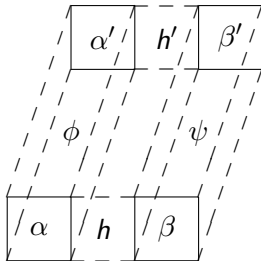
Thus $\rho(X, A, C)$ has in dimension 2

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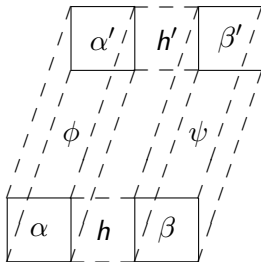
Thus $\rho(X, A, C)$ has in dimension 2 **compositions in directions 1,2**

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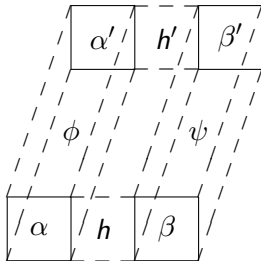
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Thus $\rho(X, A, C)$ has in dimension 2 **compositions in directions 1,2** satisfying the **interchange law** and is a **double groupoid**, containing as a **substructure** $\pi_2(X, A, x), x \in C$ and $\pi_1(A, C)$.

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In dimension 1, we still need the 2-dimensional notion of
commutative square:

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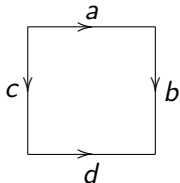
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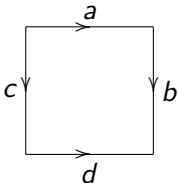
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$$ab = cd \quad a = cdb^{-1}$$

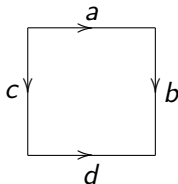
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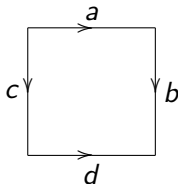
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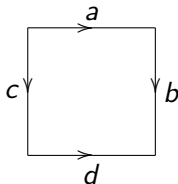
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The commutative squares in a category form a double category!
Compare Stokes' theorem! Local Stokes implies global Stokes.

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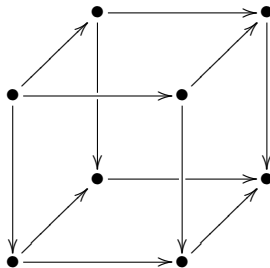
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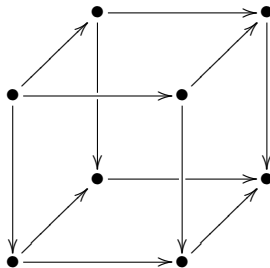
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What is a commutative cube?



What is a commutative cube?



We want the faces to commute!

we might say the top face is the composite of the other faces:

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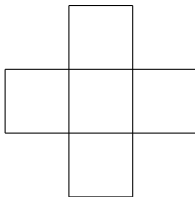
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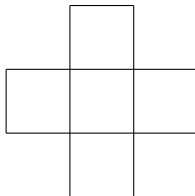
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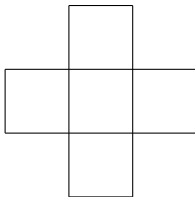


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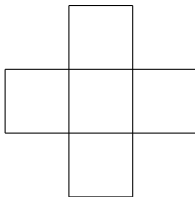
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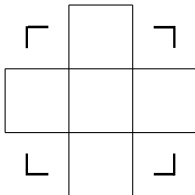


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To resolve this, we need some special squares called **thin**:
First the easy ones:

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$$\begin{pmatrix} 1 & 1 & 1 \\ & 1 & \\ & & 1 \end{pmatrix}$$

$$\begin{pmatrix} a & 1 & a \\ & 1 & \\ & & a \end{pmatrix}$$

$$\begin{pmatrix} 1 & b & 1 \\ & b & \\ & & 1 \end{pmatrix}$$

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\equiv or $\varepsilon_2 a$

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laws

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$\bar{\quad}$ or $\varepsilon_2 a$

$$[a \quad \bar{\quad}] = a$$

$$\begin{pmatrix} 1 & b & 1 \\ & b & \end{pmatrix}$$

$| \quad |$ or $\varepsilon_1 b$

$$\begin{bmatrix} b \\ | \quad | \end{bmatrix} = b$$

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$$\square$$

laws

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$$\bar{=} \text{ or } \varepsilon_2 a$$

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These are the **connections**

$$\begin{pmatrix} 1 & b & 1 \\ & b & \end{pmatrix}$$

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$$\begin{pmatrix} 1 & b & 1 \\ & b & \end{pmatrix}$$

$| \quad |$ or $\varepsilon_1 b$

$$\begin{bmatrix} b \\ | \quad | \end{bmatrix} = b$$

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It is a good exercise to prove that any composition of
commutative cubes is commutative.

Rotations in a double groupoid with connections

To show some 2-dimensional rewriting, we consider the notion of **rotations** σ, τ of an element u in a double groupoid with connections:

$$\sigma(u) = \begin{bmatrix} \llcorner & \lrcorner & \dashv \\ \lrcorner & u & \lrcorner \\ \dashv & \lrcorner & \llcorner \end{bmatrix} \quad \text{and} \quad \tau(u) = \begin{bmatrix} \dashv & \lrcorner & \llcorner \\ \lrcorner & u & \lrcorner \\ \llcorner & \lrcorner & \dashv \end{bmatrix}.$$

For any $u, v, w \in G_2$,

$$\sigma([u, v]) = \begin{bmatrix} \sigma u \\ \sigma v \end{bmatrix} \quad \text{and} \quad \sigma \left(\begin{bmatrix} u \\ w \end{bmatrix} \right) = [\sigma w, \sigma u]$$

$$\tau([u, v]) = \begin{bmatrix} \tau v \\ \tau u \end{bmatrix} \quad \text{and} \quad \tau \left(\begin{bmatrix} u \\ w \end{bmatrix} \right) = [\tau u, \tau w]$$

whenever the compositions are defined.

Further $\sigma^2 \alpha = -_1 -_2 \alpha$, and $\tau \sigma = 1$.

To prove the first of these one has to rewrite $\sigma(u +_2 v)$ until one ends up with an array, shown on the next slide, which can be reduced in a different way to $\sigma u +_2 \sigma v$. Can you identify σu , σv in this array? This gives some of the flavour of this 2-dimensional algebra of double groupoids.

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When interpreted in $\rho(X, A, C)$ this algebra implies the existence, even construction, of certain homotopies which may be difficult to do otherwise.

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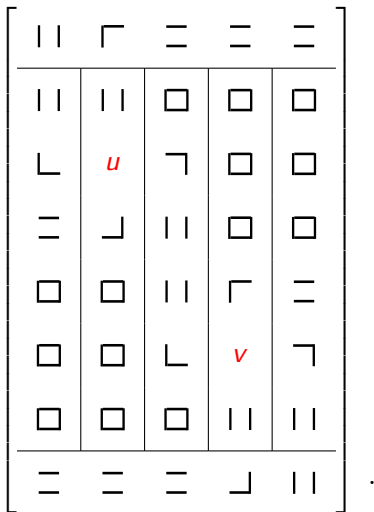
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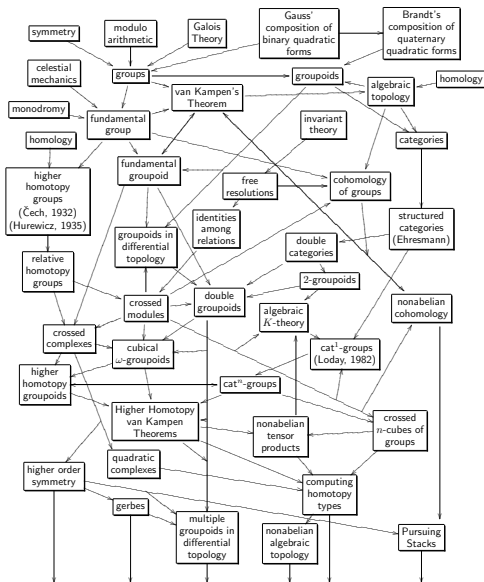
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